

Positioner Operating Handbook

Introduction and Scope

This page is intended as the basis for an Observer's Handbook. Sections will be in separate pages, linked from here.

Sections

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[Anatomy of a Fibre Move](#)

[Positioner Coordinate Systems](#)

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[Gripper Camera Measurements](#)

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[How to run with only one robot](#)

[Quick Guide to Python Routines](#)

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